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/*
  AnalogReadSerial

  Reads an analog input on pin 0, prints the result to the Serial
  Monitor.
  Graphical representation is available using Serial Plotter (Tools >
  Serial Plotter menu).
  Attach the center pin of a potentiometer to pin A0, and the outside
  pins to +5V and ground.

  This example code is in the public domain.

  http://www.arduino.cc/en/Tutorial/AnalogReadSerial
*/
const int trigPin = 11;           //connects to the trigger pin on the
distance sensor
const int echoPin = 12;          //connects to the echo pin on the
distance sensor
// the setup routine runs once when you press reset:

float distance = 0;              //stores the distance measured by
the distance sensor

int speakerPin = 10;             //the pin that buzzer is connected
to

void setup()
{
  Serial.begin (9600);           //set up a serial connection with the
computer

  pinMode(trigPin, OUTPUT);      //the trigger pin will output pulses of
electricity
  pinMode(echoPin, INPUT);       //the echo pin will measure the duration
of pulses coming back from the distance sensor
  pinMode(speakerPin, OUTPUT);   //set the output pin for the speaker
}

// the loop routine runs over and over again forever:

void loop() {

  distance = getDistance();      //variable to store the distance
measured by the sensor

  Serial.print(distance);        //print the distance that was measured
  Serial.println(" in");        //print units after the distance

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// read the input on analog pin 0:
int sensorValue = analogRead(A0); // 0 - 1023 (0 to 5V)

// make brightness change according to sensorValue
// analogWrite(9, sensorValue/4 ); // 0 - 255 (0 to 5V)
// better way:
// brightness = map(sensorValue, 0, 890);
// 0,255)
// print out the value you read:

Serial.print(sensorValue);
Serial.print(" & ");
Serial.println(distance);

delay(500); // delay in between reads for stability
//
if (distance<=1) {

play('g', 2); //ha
play('g', 1); //ppy
play('a', 4); //birth
play('g', 4); //day
play('C', 4); //to
play('b', 4); //you

play(' ', 2); //pause for 2 beats

play('g', 2); //ha
play('g', 1); //ppy
play('a', 4); //birth
play('g', 4); //day
play('D', 4); //to
play('C', 4); //you

play(' ', 2); //pause for 2 beats

play('g', 2); //ha
play('g', 1); //ppy
play('G', 4); //birth
play('E', 4); //day
play('C', 4); //dear
play('b', 4); //your
play('a', 6); //name

play(' ', 2); //pause for 2 beats

play('F', 2); //ha
play('F', 1); //ppy

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    play('E', 4);      //birth
    play('C', 4);      //day
    play('D', 4);      //to
    play('C', 6);      //you

}
Serial.print(sensorValue);
Serial.print(" & ");
Serial.println(distance);

delay(500);          // delay in between reads for stability
}

void play( char note, int beats)
{
    int numNotes = 14; // number of notes in our note and frequency
    array (there are 15 values, but arrays start at 0)

    //Note: these notes are C major (there are no sharps or flats)

    //this array is used to look up the notes
    char notes[] = { 'c', 'd', 'e', 'f', 'g', 'a', 'b', 'C', 'D', 'E',
    'F', 'G', 'A', 'B', ' ' };
    //this array matches frequencies with each letter (e.g. the 4th note
    is 'f', the 4th frequency is 175)
    int frequencies[] = {131, 147, 165, 175, 196, 220, 247, 262, 294,
    330, 349, 392, 440, 494, 0};

    int currentFrequency = 0; //the frequency that we find when we
    look up a frequency in the arrays
    int beatLength = 150; //the length of one beat (changing this will
    speed up or slow down the tempo of the song)

    //look up the frequency that corresponds to the note
    for (int i = 0; i < numNotes; i++) // check each value in notes
    from 0 to 14
    {
        if (notes[i] == note) // does the letter passed to the
        play function match the letter in the array?
        {
            currentFrequency = frequencies[i]; // Yes! Set the current
            frequency to match that note
        }
    }
}

//play the frequency that matched our letter for the number of beats
passed to the play function

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    tone(speakerPin, currentFrequency, beats * beatLength);
    delay(beats * beatLength); //wait for the length of the tone so
that it has time to play
    delay(50);                //a little delay between the notes makes
the song sound more natural
}

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//RETURNS THE DISTANCE MEASURED BY THE HC-SR04 DISTANCE SENSOR
float getDistance()
{
    float echoTime;                //variable to store the time it
takes for a ping to bounce off an object
    float calculatedDistance;      //variable to store the distance
calculated from the echo time

    //send out an ultrasonic pulse that's 10ms long
    digitalWrite(trigPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigPin, LOW);

    echoTime = pulseIn(echoPin, HIGH); //use the pulsein command to
see how long it takes for the
    //pulse to bounce back to the sensor

    calculatedDistance = echoTime / 148.0; //calculate the distance of
the object that reflected the pulse (half the bounce time multiplied
by the speed of sound)

    return calculatedDistance;      //send back the distance
that was calculated
}

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